A catalogue of simulated jerks from a geodynamo model approaching Earth's core conditions

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4DEarth_Swarm_Core ESA project deliverable D-E.1

1 General description

This document refers to publicly available output data from a geodynamo simulation that approaches closely to the physical conditions of Earth's core. In the model parameter space, this model is part of a series that defines a path connecting the conditions where classical dynamo models are found to those of the Earth's core. The theoretical definition of this path may be found in Aubert et al. (2017), and the model described here is located at 71% of this path (path parameter $\epsilon = 10^{-5}$). This model is fully described in Aubert & Gillet (2021). Table 1 lists the key time scales and associated dimensionless numbers of this model together with those expected at Earth's core conditions.

From the dimensionless outputs of the numerical model, the provided data files are already scaled to dimensional values. Here I mention some details for the re-scaling procedure that has been applied. Re-scaling can be done in a completely self-consistent manner only once the model conditions reach those of the Earth's core. The path theory serves to rescale these quantities in a way that rationalizes the gap that still exists between those two conditions (Aubert, 2018, 2020). For the time series presented here, the time basis is provided by the choice of the magnetic diffusivity η in table 1. From there and the value of the magnetic Reynolds number Rm immediately follow the determination of the core overturn time τ_U involving the root-mean-squared flow velocity U in the shell and the re-scaling of the velocity field. The value of the Lundquist number gives access to the Alfvén time τ_A , which however differs from its target Earth value as we are not yet at the end of the path. The r.m.s dimensional magnetic field amplitude B can therefore be obtained by considering that the density ρ of the simulated fluid shell is $(5.8/2)^2$ time stronger than its Earth counterpart $\rho = 11000 \text{ kg/m}^3$, this former factor accounting for the differences in the model and Earth Alfvén times. Finally, the density anomaly field is rescaled following Aubert & Gillet (2021), by expressing the dimensionless field in units of $\rho\Omega\eta/g_oD$ (where g_o is the gravity at the core surface), and multiplying

Quantity	Definition	71% of path model	Earth's core
Earth radius	а	6371.2 km	6371.2 km
core surface radius	r_o	3485 km	3485 km
outer core thickness	D	2260 km	2260 km
magnetic diffusivity	η	$1.2 \text{ m}^2/\text{s}$	$\approx 1.2 \text{ m}^2/\text{s}$
magnetic diffusion time	$\tau_\eta = D^2/\eta$	135000 yr	≈ 135000 yr
planetary rotation period	$2\pi\tau_\Omega=2\pi/\Omega$	12 days	1 day
Alfvén time	$\tau_A = \sqrt{\rho \mu} D/B$	5.8 yr	$\approx 2 \text{ yr}$
1D Alfvén speed	$D/\sqrt{3}\tau_A$	225 km/yr	$\approx 650 \text{ km/yr}$
core overturn time	$\tau_U = D/U$	118 yr	$\approx 120 \text{ yr}$
1D convective speed	$D/\sqrt{3}\tau_U$	11 km/yr	$\approx 11 \text{ km/yr}$
Magnetic Ekman number	$E/Pm=\tau_\Omega/\tau_\eta$	3.8 10 ⁻⁸	$\approx 3.2 \ 10^{-9}$
Magnetic Reynolds number	$Rm = \tau_{\eta}/\tau_U$	1140	≈ 1100
Lundquist number	$S = au_\eta / au_A$	23300	≈ 68000

Table 1

Key parameters for the model, presented together with their model values and values expected at Earth's core conditions. B and U are root-mean-squared amplitudes of the magnetic field inside the simulated core.

the result with Earth's core dimensional estimate for $\rho\Omega\eta/g_oD$ obtained with $g_o = 10 \text{ m/s}^2$, $\rho = 11000 \text{ kg/m}^3$ and the other values from Table 1.

Figure 1 presents temporal sequences of the core-mantle boundary secular acceleration energy (as defined in Aubert, 2018) and Earth-surface jerk energy (as defined in Aubert & Finlay, 2019). The outputs that are made available here specifically focus on the 14 simulated geomagnetic jerk events marked with arrows in Figure 1. These ouputs first consist in high-resolution time series of the coefficents describing the poloidal magnetic field outside the core and the velocity field at the core surface. The time series cover a few decades before and after the approximate timestamps of jerks presented in Table 2. Their temporal resolution is set to 0.05 years i.e. four times finer than the long time series covering the entire sequence that were previously provided in deliverable D-C.1. The model operates with stress-free boundary conditions, which implies that Ekman boundary layers are not described and that the core surface directly corresponds to the free stream. For each jerk event, a collection of movies representing these time series is also provided. Finally, full three-dimensional states of the simulation at selected times are provided for a selection of jerks.



Fig. 1. Core-mantle boundary (CMB) secular acceleration energy (top) and Earth-surface jerk energy (bottom), as functions of the dimensional simulation time. See Aubert (2018); Aubert & Finlay (2019) for definitions. Following these references, the outputs on this figure have been truncated at spherical harmonic degree and order 13, but the publicly available outputs are supplied up to a higher spherical harmonic resolution of 30.

Jerk No.	timestamp (years)	Jerk No.	timestamp (years)
1	4600	8	7840
2	5750	9	8880
3	2920	10	9673
4	1915	11	10590
5	6490	12	12620
6	7300	13	13411
7	7620	14	13546
Table 2			

Table 2

Approximate timestamps for simulated jerks in the catalogue.

2 Data format and description

2.1 Magnetic field coefficients

To describe the magnetic field at and above the core surface, we adopt the classical Gauss coefficient description for the magnetic field. Denoting the colatitude as θ and the Greenwich-centered longitude as φ , the poloidal field at a radius *r* above the core-mantle boundary may be written

$$\mathbf{B}_{p}(r,\theta,\varphi,t) = -\boldsymbol{\nabla}V \tag{1}$$

where

$$V(r,\theta,\varphi,t) = a \sum_{l=1}^{30} \left(\frac{a}{r}\right)^{l+1} \sum_{m=0}^{l} \left[g_l^m(t)\cos m\varphi + h_l^m(t)\sin m\varphi\right] P_l^m(\cos\theta).$$
(2)

Here t is time, a = 6371.2 km is Earth's magnetic radius of reference, P_l^m is the Schmidt-seminormalised Legendre function of degree l and order m.

For each jerk event, the file Gauss_Bsurf.mat (MATLAB data format) comprises the dimensional timestamp vector timers (in years) containing the discrete values of t and an array gnm containing the coefficients $g_l^m(t)$, $h_l^m(t)$ (in nanoteslas) arranged according to:

$$gnm(:, 1) = g_1^0(t)$$

$$gnm(:, 2) = g_1^1(t)$$

$$gnm(:, 3) = h_1^1(t)$$

$$gnm(:, 4) = g_2^0(t)$$

$$gnm(:, 5) = g_2^1(t)$$

$$gnm(:, 6) = h_2^1(t)$$

$$gnm(:, 7) = g_2^2(t)$$

$$gnm(:, 8) = h_2^2(t)$$
...
$$gnm(:, 959) = g_{30}^{30}(t)$$

$$gnm(:, 960) = h_{30}^{30}(t)$$

Note that the sinus coefficients corresponding to m = 0 are not stored as they vanish identically. There are therefore 960 coefficients corresponding to a description of the output up to spherical harmonic degree and order 30. The core surface poloidal magnetic field is then obtained by setting r to $r_o = 3485$ km in equation (2).

2.2 Velocity field coefficients

The core surface velocity field coefficients are described using the spheroidaltoroidal formalism. The θ and φ components of the core surface velocity vector **u** are written

$$\mathbf{u} = \begin{pmatrix} u_{\theta} = \frac{1}{\sin\theta} \frac{\partial T}{\partial \varphi} + \frac{\partial S}{\partial \theta} \\ u_{\varphi} = -\frac{\partial T}{\partial \theta} + \frac{1}{\sin\theta} \frac{\partial S}{\partial \varphi} \end{pmatrix}$$
(3)

The spectral decomposition of T, S obeys

$$T = \sum_{l=1}^{30} \sum_{m=0}^{l} \left[t c_l^m(t) \cos m\varphi + t s_l^m(t) \sin m\varphi \right] P_l^m(\cos \theta)$$
(4)

$$S = \sum_{l=1}^{30} \sum_{m=0}^{l} \left[sc_l^m(t) \cos m\varphi + ss_l^m(t) \sin m\varphi \right] P_l^m(\cos \theta)$$
(5)

For each jerk event, the file Gauss_Vsurf.mat (MATLAB data format) contains the timestamp timers (in years) together with two arrays tnm and snm (in km.rad/yr) where the coefficients tc_l^m , ts_l^m and sc_l^m , ss_l^m are respectively stored. The ordering follows that of the magnetic field Gauss coefficients i.e.

$$\begin{aligned} & \operatorname{tnm}(:,1) = tc_1^0(t) \\ & \operatorname{tnm}(:,2) = tc_1^1(t) \\ & \operatorname{tnm}(:,3) = ts_1^1(t) \\ & \operatorname{tnm}(:,4) = tc_2^0(t) \\ & \operatorname{tnm}(:,5) = tc_2^1(t) \\ & \operatorname{tnm}(:,6) = ts_2^1(t) \\ & \operatorname{tnm}(:,7) = tc_2^2(t) \\ & \operatorname{tnm}(:,8) = ts_2^2(t) \\ & \cdots \\ & \operatorname{tnm}(:,959) = tc_{30}^{30}(t) \\ & \operatorname{tnm}(:,960) = ts_{30}^{30}(t) \end{aligned}$$

Note that the sinus coefficients corresponding to m = 0 are not stored as they vanish identically. As for the magnetic field coefficients above there are 960 coefficients for each scalar, corresponding to a description of the output up to spherical harmonic degree and order 30.

2.3 Movies

For each jerk event, a .zip archive is provided that contains the following mp4 movie files:

- Brcmb.mov and Brcmb13.mov: core surface radial magnetic field (in mT), respectively at native (up to spherical harmonic degree 170) and truncated (up to spherical harmonic degree 13) resolutions,
- Vpcmb.mov: core surface azimuthal velocity field (in km/yr) at native resolution,
- dVcmb.mov: core surface azimuthal velocity acceleration (in km/yr²) at native resolution,
- SVcmb.mov: core surface radial secular variation (first time derivative of the magnetic field, in μT/yr) up to spherical harmonic degree 13,
- SAcmb.mov and SAsurf.mov: core surface and Earth surface radial secular acceleration (second time derivative of the magnetic field, in nT/yr²) up to spherical harmonic degree 13.

2.4 Full three-dimensional states

For jerks 1,3 and 9, two states of the simulations at native spatial resolution are provided as (very large) binary files Gt1 and Gt2. The two states are closely spaced in time such that a time derivative can be reliably computed. The states can be loaded into computer memory by using the provided matlab script parodyload_scaled.m.

Once loaded, the following variables are present in MATLAB memory:

- the dimensional timestamp timers (in years),
- the numbers of grid points nr=1248 in radius, nt=256 in latitude and np=512 in longitude, with longitude np=1 referring to 180 degrees East in the Pacific.
- the vectors r(1:nr) of radii within the outer core (in km), theta(1:nt) of colatitudes and phi(1:np) of longitudes (both in radians) defining the spherical coordinate frame,
- the three (1:np,1:nt,1:nr) arrays Vr,Vt,Vp of the outer core velocity field components (in km/yr),
- the three (1:np,1:nt,1:nr) arrays Br,Bt,Bp of the outer core magnetic field components (in mT),
- the (1:np,1:nt,1:nr) array T of the outer core scalar density anomaly field (in kg/m³). Note that this latter quantity is relative i.e. it can be shifted by an arbitrary constant (only the gradients matter).

References

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